AMENDMENT TO THE CLAIMS:

Please amend claims 1, 4-6, 10 and 16-18 as follows:

1. (Currently amended) A method for processing data to provide a forewarning of a critical event, comprising:

acquiring a plurality of sets of data for at least one a plurality of channels of data for at least one test subject or process;

calculating a set of channel data for a selected parameter from the plurality of channels of data representing parameters that are calculated to provide the selected parameter;

computing a renormalized measure of dissimilarity from distribution functions derived from a phase space for each respective the selected channel of data;

comparing said renormalized measure of dissimilarity to a threshold (U_c) for a number of occurrences (N_{occ}) to indicate a condition change in said renormalized measure of dissimilarity; and

detecting a simultaneous condition change in a plurality (N_{SIM}) of renormalized measures of dissimilarity to determine a forewarning of the critical event; and

wherein said one channel of data corresponds to a parameter that is calculated from a plurality of parameters corresponding to a plurality of channels of data.

- 2. (Original) The method of claim 1, wherein the test subject is a human patient.
- 3. (Original) The method of claim 1, wherein the test subject is a mechanical device or physical process.
- 4. (Currently amended) The method of claim 1, wherein the selected parameter process indicative data is three-phase electrical power.
 - 5. (Currently amended) The method of claim 1, wherein the

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<u>selected</u> <u>parameter</u> <u>process indicative data</u> is vibration mechanical power.

- 6. (Currently amended) The method of claim 1, wherein the <u>selected parameter process indicative data</u> is a difference between two channels of EEG data.
- 7. (Original) The method of claim 1, further comprising: performing a first filtering of each set of data with a zero-phase quadratic filter that filters out high-frequency artifacts; and

performing a second filtering of each set of data with a zero-phase quadratic filter to filter out low-frequency artifacts.

8. (Original) The method of claim 1, further comprising: sorting the data values into ascending order from a minimum to a maximum;

determining the number of unique signal values (n) and the corresponding relative occurrence frequency (F_k) for each unique signal value (v_k) ;

displaying a graph of frequency (F_k) versus values (v_k) in each bin in a connected phase space; and

discarding data that has $[v_k - (N/n)]/\sigma_3 > z$, where the value of z is determined by solving $1/n = \frac{1}{2} \operatorname{erfc}(z/\sqrt{2})$, and σ_3 is the standard deviation in the occurrence frequency.

9. (Original) The method of claim 1, with an alternative embodiment for event forewarning, comprising determining a sequence of renormalized phase space dissimilarity measures from data sets for the test subject or process; summing said renormalized measures into a composite measure, C_i , for the *i*-th data set; performing a least-squares analysis over a window of m points of the said composite measure to obtain a straight line, $y_i=ai+b$, that best fits said composite data in a least-squares

sense; determining the variance, ${\sigma_1}^2 = \Sigma_i (y_i - C_i)^2/(m-1)$, of said composite measure with respect to the straight line fit; obtaining the variability of the sequel window of m sequential points via the statistic, $G = \sum_{i} (y_{i} - C_{i})^{2}/\sigma_{1}^{2}$; comparing said value of G to the running maximum value of the same statistic, G_{max} ; determining the forewarning of or failure onset of a critical event (such as a machine failure), when significantly more than Gmax; obtaining the ratio, $(G_{max})_{k}/(G_{max})_{k-1}$, of the present and previous running maximum in G; and determining the forewarning of a critical event when R is significantly more than some limit.

10. (Currently amended) A method for processing data to provide a forewarning of a critical event, comprising:

acquiring a plurality of sets of data for at least two channels of data for at least one test subject or process;

producing a set of multi-channel data representing a combination of said at least two channels of data;

computing to a multi-channel time-delay phase-space (PS) construction, which has the form: $y(i) = [s(1)_i, s(1)_{i+\lambda}, s(1)_{i+\lambda}, s(1)_{i+2\lambda}, \dots, s(2), s(2)_{i+\lambda}, s(2)_{i+2\lambda}, \dots, s(c)_i, s(c)_{i+\lambda}, s(c)_{i+2\lambda}, \dots],$ where s(c) denotes the symbolized data for c-th channel;

computing a renormalized measure of dissimilarity from distribution functions derived from the (non)connected phase space for the multi-channel of data;

comparing said renormalized measure of dissimilarity to a threshold (U_C) for a number of occurrences (N_{OCC}) to indicate a condition change in said renormalized measure of dissimilarity; and

detecting a simultaneous condition change in a plurality (N_{SIM}) of renormalized measures of dissimilarity to determine a forewarning of the critical event.

11. (Original) The method of claim 10, further comprising: performing a first filtering of each set of data with a

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zero-phase quadratic filter that filters out high-frequency artifacts; and

performing a second filtering of each set of data with a zero-phase quadratic filter to filter out low-frequency artifacts.

- (Original) The method of claim 10, using an alternative embodiment for event forewarning, comprising determining a sequence of renormalized phase space dissimilarity measures from data sets collected during increasingly severe fault conditions; summing said renormalized measures into a composite measure, Ci, for the i-th data set; performing a least-squares analysis over a window of m points of the said composite measure to obtain a straight line, $y_i=ai+b$, that best fits said composite data in a least-squares sense; determining the variance, $\sigma_1^2 = \Sigma_i$ (y_i - $(C_i)^2/(m-1)$, of said composite measure with respect to the straight line fit; obtaining the variability of a sequel window of m sequential points via the statistic, $G = \sum_{i} (y_i - C_i)^2/\sigma_1^2$; comparing said value of G to the running maximum value of the same statistic, G_{max} ; and determining the onset of a critical event, such as forewarning of a machine failure, when G is significantly more than G(non-end-of-life), or when R significantly more than R(non-end-of-life), or detection of failure onset when G is significantly greater than G(end-oflife).
- 13. (Original) The method of claim 10, wherein the test subject is a human patient.
- 14. (Original) The method of claim 10, wherein the test subject is a mechanical device or physical process.
- 15. (Original) The method of claim 10, further comprising: sorting the data values into ascending order from a minimum to a maximum;

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determining the number of unique signal values (n) and the corresponding relative occurrence frequency (F_k) for each unique signal value (v_k) ;

displaying a graph of frequency (F_k) versus values (v_k) in each bin in a connected phase space; and

discarding data that has $[v_k - (N/n)]/\sigma_3 > z$, where the value of z is determined by solving $1/n = \frac{1}{2} \operatorname{erfc}(z/\sqrt{2})$, and σ_3 is the standard deviation in the occurrence frequency.

- 16. (Currently amended) The method of claim 10, wherein the multi-channel time-delay phase-space (PS) construction is constructed from process-indicative data, which is three-phase electrical power data.
- 17. (Currently amended) The method of claim 10, wherein the multi-channel time-delay phase-space (PS) construction is constructed from process-indicative data, which is vibration mechanical power data.
- 18. (Currently amended) The method of claim 10, wherein the multi-channel time-delay phase-space (PS) construction is constructed from process-indicative data representing is a difference between the two channels of EEG data, which is EEG data.